

Features

- GPS L1 C/A Code
- Perform 8 million time-frequency hypothesis testing per second
- Open sky hot start 1 sec
- Open sky cold start 29 sec
- Signal detection better than -158dBm
- Reacquisition sensitivity -155dBm
- Accuracy 2.5m CEP
- Tracking current $< 30\text{mA}$

Sheng Jay Automation Technology Co., Ltd

Low Power Very High Performance SMD GPS Module

Sheng Jay Automation co., ltd manufacture various GPS related products, from start to finish. We also provide GPS module solution intended for a broad range of Original Equipment Manufacturer (OEM) products, where fast and easy system integration and minimal development risk is required.

The Sheng Jay Automation GPS receiver's -158dBm tracking sensitivity allows continuous position coverage in nearly all application environments. Its high performance search engine is capable of testing 8,000,000 time-frequency hypotheses per second, offering industry-leading signal acquisition and TTFF speed.

The receiver is optimized for applications requiring high performance, low power, and low cost; suitable for a wide range of OEM configurations including mobile phone, PND, asset tracking, and vehicle navigation products.

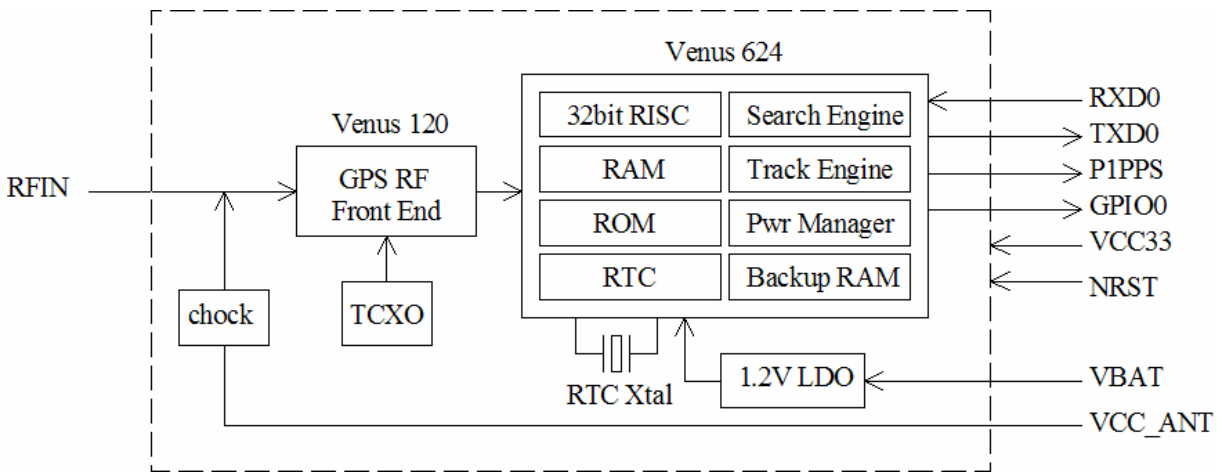
The very small 13mm x 15mm form factor and the SMT pads allow standard surface mount device pick-and-place process in fully automated assembly process; enabling high-volume, very cost-efficient production.

TECHNICAL SPECIFICATIONS

Receiver Type	L1 C/A code, 65-channel Venus 6 engine
Accuracy	Position 2.5m CEP Velocity 0.1m/sec Time 250ns
Startup Time	1 second hot start under open sky 29 second cold start under open sky (average)
Reacquisition	1s
Sensitivity	-155dBm acquisition *1 -158dBm tracking
Multi-path Mitigation	Advanced multi-path detection and suppression
A-GPS	Support PromptFix® AGPS
Update Rate	1Hz
Dynamics	4G (39.2m/sec ²)
Operational Limits	Altitude < 18,000m or velocity < 515m/s (COCOM limit, either may be exceeded but not both)
Serial Interface	3.3V LVTTTL level
Protocol	NMEA-0183 V3.01 GPGGA, GPGLL, GPGSA, GPGSV, GPRMC, GPVTG*2 9600 baud, 8, N, 1
Datum	Default WGS-84 User definable
Input Voltage	3.3V DC +/-10%
Input Current	~50mA acquisition ~30mA tracking
Dimension	15mm L x 13mm W
Weight:	2g
Operating Temperature	-40°C ~ +85°C
Storage Temperature	-55 ~ +100°C
Humidity	5% ~ 95%

*1: 1 satellite at -138dBm, all others at -155dBm
 *2: GPGGA, GPGSA, GPGSV, GPRMC are default output message

BLOCK DIAGRAM



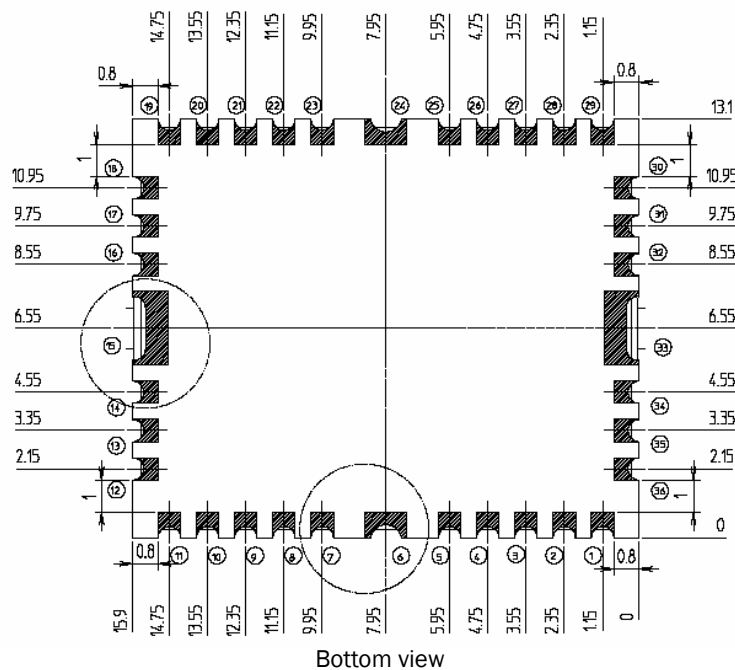
Module block schematic

ANTENNA

The Sheng Jay Automation module is designed to work active antenna. Recommended active should have gain of 15 ~ 30dB and noise figure less than 2dB.

MECHANICAL CHARACTERISTICS

Unit: mm



PINOUT DESCRIPTION

Pin No.	Name	Description
1	RFIN	GPS RF input, connect to active antenna
2	AGND	Ground
3	AGND	Ground
4	AGND	Ground
5	VBAT	Backup supply voltage for RTC and backup memory, minimum 2.0V
6	GND	Chassis ground
7	NC	No connection
8	AGND	Ground
9	AGND	Ground
10	AGND	Ground
11	VCC33	Main 3.3V supply input
12	AGND	Ground
13	RSTN	External active-low reset input. Only needed when power supply rise time is very slow.
14	AGND	Ground
15	GND	Chassis ground
16	NC	No connection
17	AGND	Ground
18	GPIO	General Purpose Input Output (reserved for GPS status LED indicator)
19	AGND	Ground
20	P1PPS	1 pulse per second time mark
21	AGND	Ground
22	AGND	Ground
23	AGND	Ground
24	GND	Chassis ground
25	NC	No connection
26	AGND	Ground
27	NC	No connection
28	AGND	Ground
29	AGND	Ground
30	TXD0	UART output, 3.3V I/O
31	RXD0	UART input, 3.3V I/O
32	NC	No connection
33	GND	Chassis ground
34	NC	No connection
35	AGND	Ground
36	AGND	Ground

NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org

GGA - Global Positioning System Fix Data

Time, position and fix related data for a GPS receiver.

Structure:

\$GPGGA,hhmmss.sss,ddmm.mmmm,a,dddmm.mmmm,a,x,xx,x.x,x.x,M,,,,xxx*hh<CR><LF>
1 2 3 4 5 6 7 8 9 10 11

Example:

\$GPGGA,111636.932,2447.0949,N,12100.5223,E,1,11,0.8,118.2,M,,,,0000*02<CR><LF>

Field	Name	Example	Description
1	UTC Time	111636.932	UTC of position in hhmmss.sss format, (000000.000 ~ 235959.999)
2	Latitude	2447.0949	Latitude in ddmm.mmmm format Leading zeros transmitted
3	N/S Indicator	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	Longitude	12100.5223	Longitude in dddmm.mmmm format Leading zeros transmitted
5	E/W Indicator	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	GPS quality indicator	1	GPS quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode 3: GPS PPS Mode, fix valid 4: Real Time Kinematic. System used in RTK mode with fixed integers 5: Float RTK. Satellite system used in RTK mode. Floating integers 6: Estimated (dead reckoning) Mode 7: Manual Input Mode 8: Simulator Mode
7	Satellites Used	11	Number of satellites in use, (00 ~ 12)
8	HDOP	0.8	Horizontal dilution of precision, (00.0 ~ 99.9)
9	Altitude	108.2	mean sea level (geoid), (-9999.9 ~ 17999.9)
10	DGPS Station ID	0000	Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used
11	Checksum	02	

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The checksum is the exclusive OR of all characters between '\$' and '*'.

GLL - Latitude/Longitude

Latitude and longitude of current position, time, and status.

Structure:

\$GPGLL,ddmm.mmmmm,a,dddmm.mmmmm,a,hhmmss.sss,A,a*hh<CR><LF>
 1 2 3 4 5 6 7 8

Example:

\$GPGLL,2447.0944,N,12100.5213,E,112609.932,A,A*57<CR><LF>

Field	Name	Example	Description
1	Latitude	2447.0944	Latitude in ddmm.mmmmm format Leading zeros transmitted
2	N/S Indicator	N	Latitude hemisphere indicator 'N' = North 'S' = South
3	Longitude	12100.5213	Longitude in dddmm.mmmmm format Leading zeros transmitted
4	E/W Indicator	E	Longitude hemisphere indicator 'E' = East 'W' = West
5	UTC Time	112609.932	UTC time in hhmmss.sss format (000000.000 ~ 235959.999)
6	Status	A	Status, 'A' = Data valid, 'V' = Data not valid
7	Mode Indicator	A	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
8	Checksum	57	

GSA – GNSS DOP and Active Satellites

GPS receiver operating mode, satellites used in the navigation solution reported by the GGA or GNS sentence and DOP values.

Structure:

\$GPGSA,A,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x,x,x,x,x*hh<CR><LF>
 1 2 3 3 3 3 3 3 3 3 3 3 3 3 4 5 6 7

Example:

\$GPGSA,A,3,05,12,21,22,30,09,18,06,14,01,31,,1.2,0.8,0.9*36<CR><LF>

Field	Name	Example	Description
1	Mode	A	Mode 'M' = Manual, forced to operate in 2D or 3D mode 'A' = Automatic, allowed to automatically switch 2D/3D
2	Mode	3	Fix type 1 = Fix not available 2 = 2D 3 = 3D
3	Satellite used 1~12	05,12,21,22,30,09,18,06,14,01,31,,	Satellite ID number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	PDOP	1.2	Position dilution of precision (00.0 to 99.9)
5	HDOP	0.8	Horizontal dilution of precision (00.0 to 99.9)
6	VDOP	0.9	Vertical dilution of precision (00.0 to 99.9)
7	Checksum	36	

GSV – GNSS Satellites in View

Number of satellites (SV) in view, satellite ID numbers, elevation, azimuth, and SNR value. Four satellites maximum per transmission.

Structure:

```
$GPGSV,x,x,xx,xx,xx,xxx,xx,....,xx,xx,xxx,xx *hh<CR><LF>
  1 2 3 4 5 6 7   4 5 6 7 8
```

Example:

```
$GPGSV,3,1,12,05,54,069,45,12,44,061,44,21,07,184,46,22,78,289,47*72<CR><LF>
$GPGSV,3,2,12,30,65,118,45,09,12,047,37,18,62,157,47,06,08,144,45*7C<CR><LF>
$GPGSV,3,3,12,14,39,330,42,01,06,299,38,31,30,256,44,32,36,320,47*7B<CR><LF>
```

Field	Name	Example	Description
1	Number of message	3	Total number of GSV messages to be transmitted (1-3)
2	Sequence number	1	Sequence number of current GSV message
3	Satellites in view	12	Total number of satellites in view (00 ~ 12)
4	Satellite ID	05	Satellite ID number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	Elevation	54	Satellite elevation in degrees, (00 ~ 90)
6	Azimuth	069	Satellite azimuth angle in degrees, (000 ~ 359)
7	SNR	45	C/No in dB (00 ~ 99) Null when not tracking
8	Checksum	72	

RMC – Recommended Minimum Specific GNSS Data

Time, date, position, course and speed data provided by a GNSS navigation receiver.

Structure:

```
$GPRMC,hhmmss.sss,A,dddmm.mmmm,a,dddmm.mmmm,a,x.x,x.x,ddmmyy,,,a*hh<CR><LF>
      1      2      3      4      5      6 7 8      9      10 11
```

Example:

```
$GPRMC,111636.932,A,2447.0949,N,12100.5223,E,000.0,000.0,030407,,,A*61<CR><LF>
```

Field	Name	Example	Description
1	UTC time	0111636.932	UTC time in hhmmss.sss format (000000.00 ~ 235959.999)
2	Status	A	Status 'V' = Navigation receiver warning 'A' = Data Valid
3	Latitude	2447.0949	Latitude in dddmm.mmmm format Leading zeros transmitted
4	N/S indicator	N	Latitude hemisphere indicator 'N' = North 'S' = South
5	Longitude	12100.5223	Longitude in dddmm.mmmm format Leading zeros transmitted
6	E/W Indicator	E	Longitude hemisphere indicator 'E' = East 'W' = West
7	Speed over ground	000.0	Speed over ground in knots (000.0 ~ 999.9)
8	Course over ground	000.0	Course over ground in degrees (000.0 ~ 359.9)
9	UTC Date	030407	UTC date of position fix, ddmmyy format
10	Mode indicator	A	Mode indicator 'N' = Data not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
11	checksum	61	

VTG – Course Over Ground and Ground Speed

The actual course and speed relative to the ground.

Structure:

GPVTG,x.x,T,,M,x.x,N,x.x,K,a*hh<CR><LF>
1 2 3 4 5

Example:

\$GPVTG, 000.0,T,,M,000.0,N,0000.0,K,A*3D<CR><LF>

Field	Name	Example	Description
1	Course	000.0	True course over ground in degrees (000.0 ~ 359.9)
2	Speed	000.0	Speed over ground in knots (000.0 ~ 999.9)
3	Speed	0000.0	Speed over ground in kilometers per hour (0000.0 ~ 1800.0)
4	Mode	A	Mode indicator 'N' = not valid 'A' = Autonomous mode 'D' = Differential mode 'E' = Estimated (dead reckoning) mode 'M' = Manual input mode 'S' = Simulator mode
5	Checksum	3D	

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